* Class motor
  + Public:
    - Motor\_pins
    - Button\_pins
    - Set motor\_pins as output
    - Set button\_pins as input
    - Function Update()
      * Check if both CCW and CW button is pressed
        + Do nothing
      * Else If CW is pressed
        + Write to CWP & CWM pin
        + MotorRun()
      * Else If CCW is pressed
        + Write to CWP & CWM pin
        + MotorRun()
      * Else
        + MotorOff()
  + Private:
    - MotorRun()
    - MotorOff()